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Chapter 2: Distributed Systems: Interprocess communication

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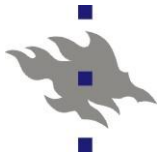
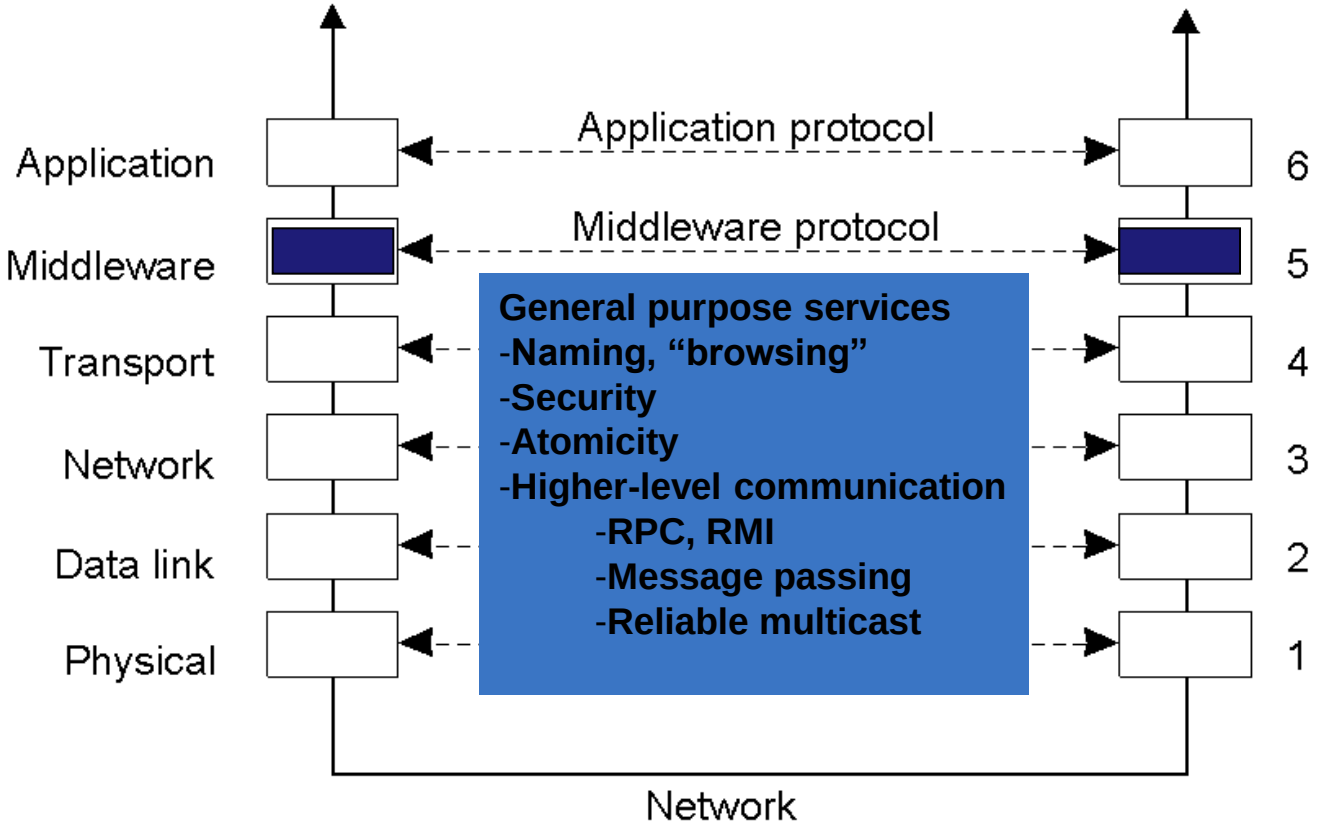
Slides joint work with Jussi Kangasharju et al.



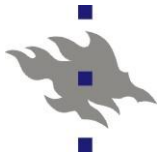
Chapter Outline

- Overview of interprocess communication
- Remote invocations (RPC etc.)
- Persistence and synchronicity

Middleware Protocols

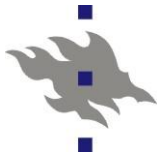


An adapted reference model for networked communication.



Remote Procedure Calls

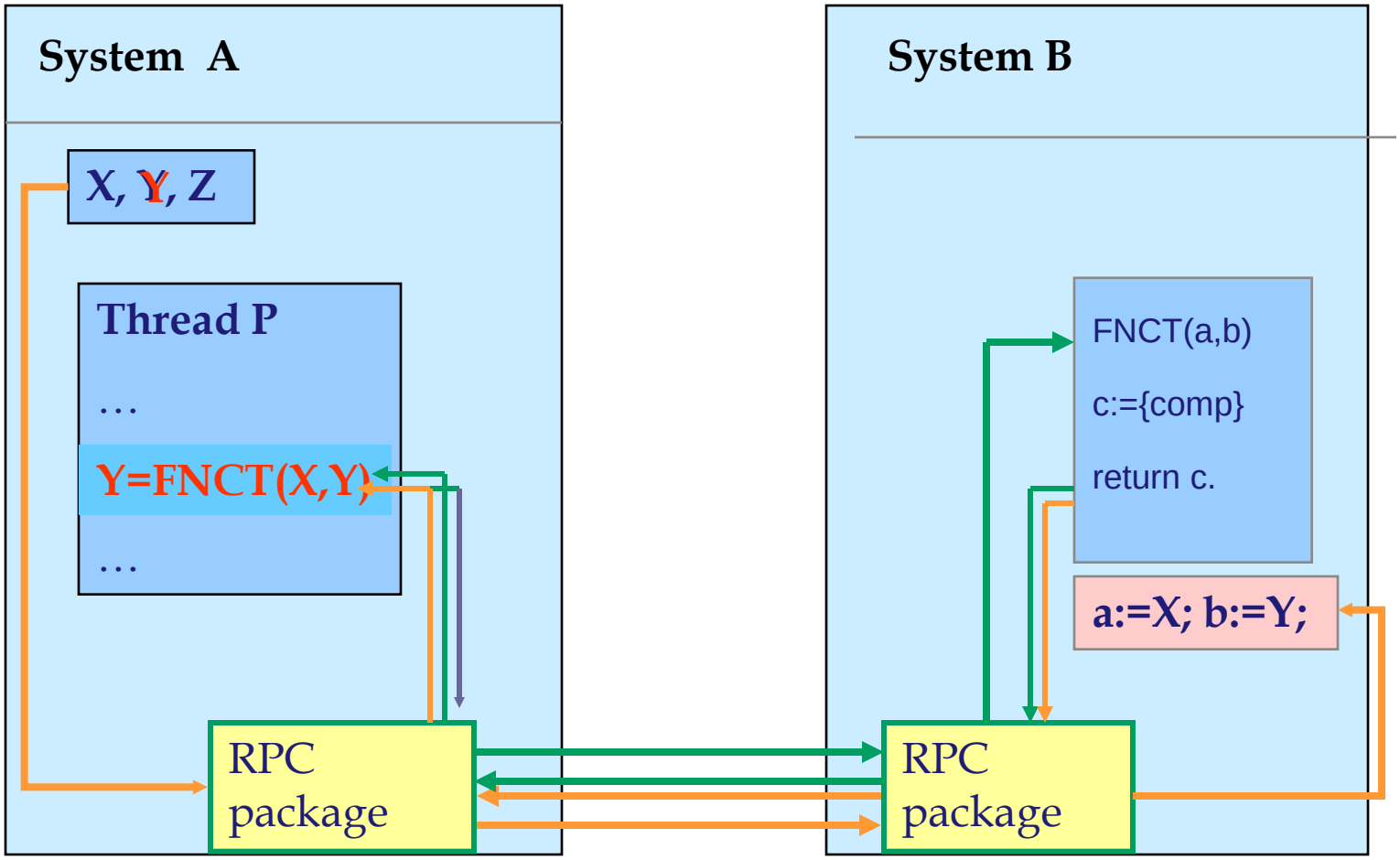
- Basic idea:
  - “passive” routines
  - Available for remote clients
  - Executed by a local worker process, invoked by local infrastructure
- See examples in book

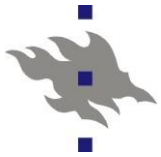


RPC goals

- Achieve access transparent procedure call
- Cannot fully imitate local calls:
  - Naming, failures, performance
  - Global variables, context dependent variables, pointers
  - Call-by-reference vs. call-by-value
- Call semantics
  - Maybe, at-least-once, at-most-once
  - Exception delivery
- Can be enhanced with other properties
  - Asynchronous RPC
  - Multicast, broadcast
  - Location transparency, migration transparency, …
  - Concurrent processing

RPC: a Schematic View

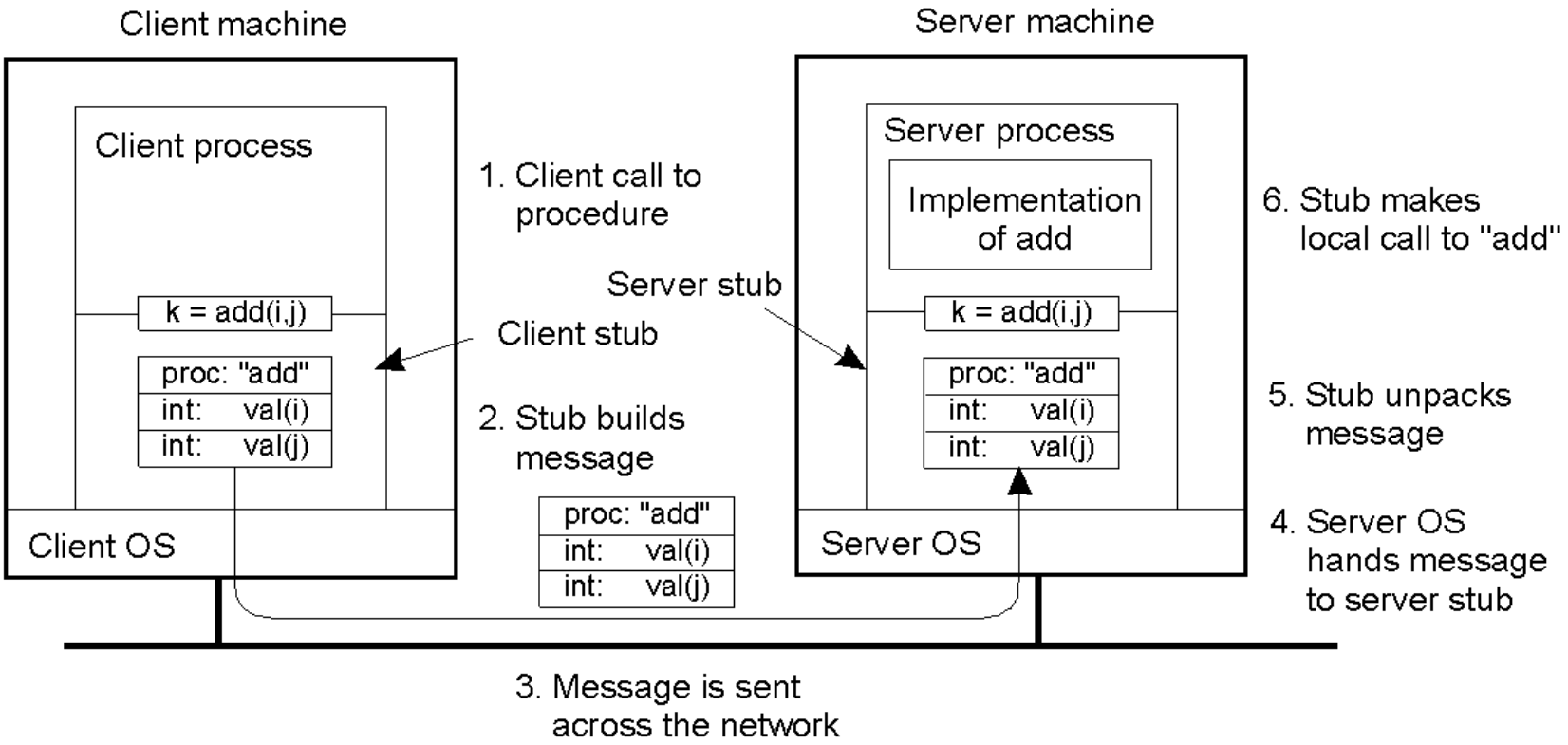




Implementation of RPC

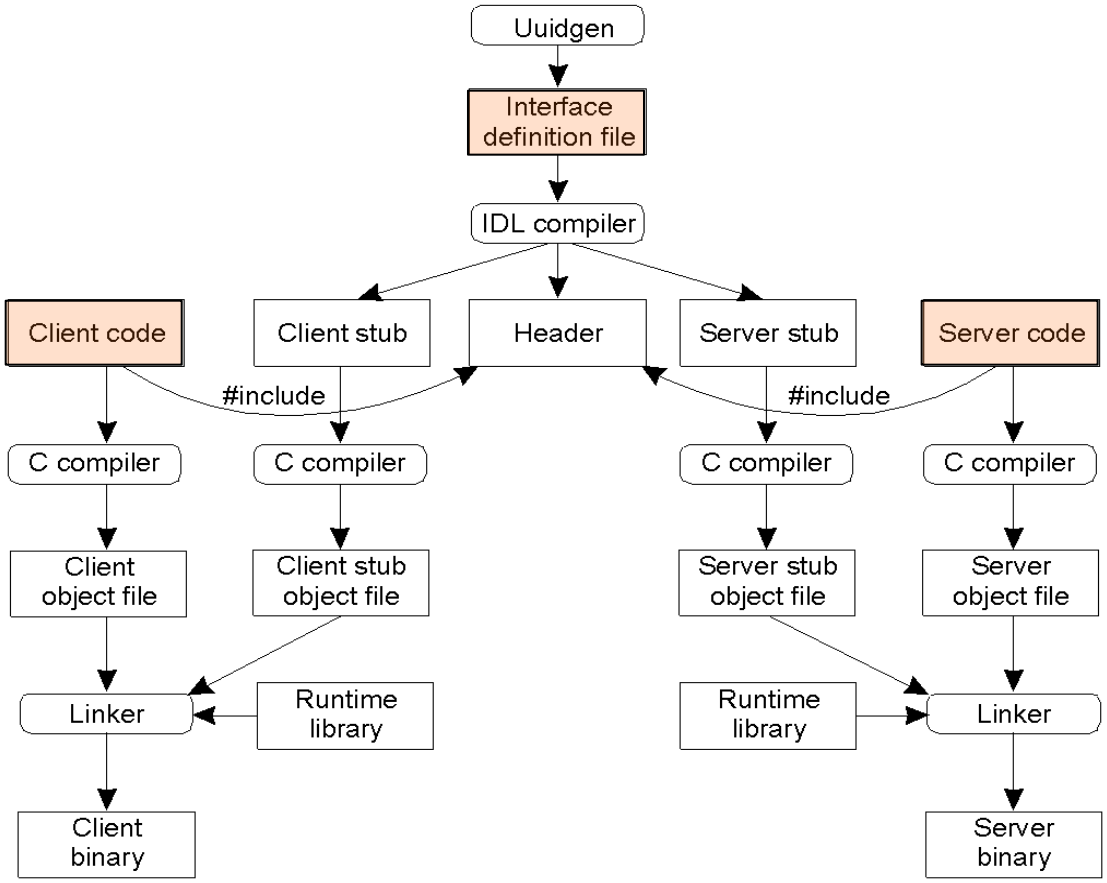
- RPC components:
  - RPC Service (two stubs)
    - interpretation of the service interface
    - packing of parameters for transportation
  - Transportation service: node to node
    - responsible for message passing
    - part of the operating system
- Name service: look up, binding
  - name of procedure, interface definition

Passing Value Parameters

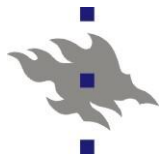


Steps involved in doing remote computation through RPC

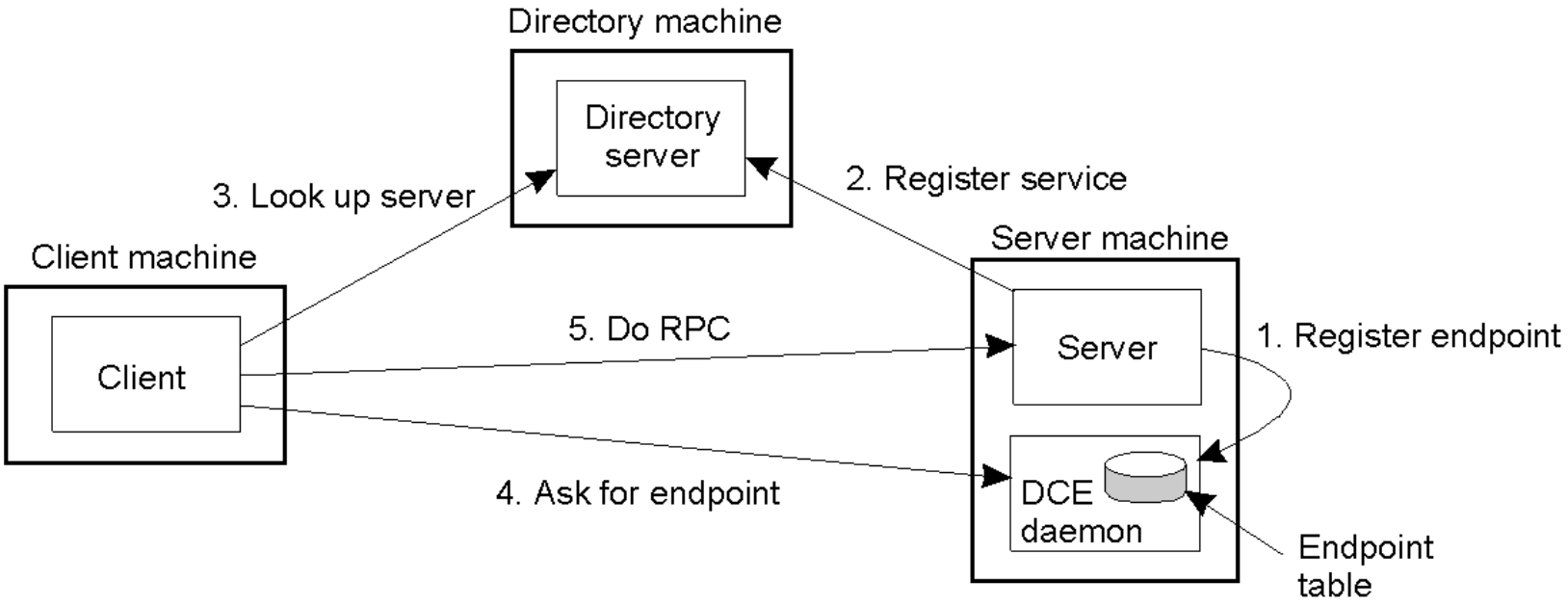
Writing a Client and a Server



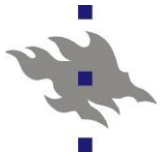
The steps in writing a client and a server in DCE RPC.



Binding a Client to a Server

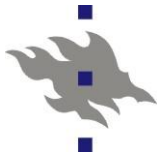


Example: Client-to-server binding in DCE.



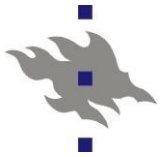
Implementation of RPC

- Server: who will execute the procedure?
- One server process
  - infinite loop, waiting in “receive”
  - call arrives : the process starts to execute
  - one call at a time, no mutual exclusion problems
- A process is created to execute the procedure
  - parallelism possible
  - overhead
  - mutual exclusion problems to be solved
- One process, a set of thread skeletons:
  - one thread allocated for each call



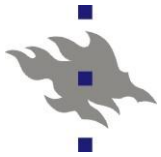
Design Issues

- Language independent interface definition
- Exception handling
- Delivery guarantees
  - RPC / RMI semantics
  - maybe
  - at-least-once
  - at-most-once
  - (un-achievable: exactly-once)
- Transparency (algorithmic vs. behavioral)



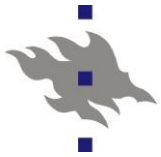
RPC: Types of failures

- Client unable to locate server
- Request message lost
  - retransmit a fixed number of times
- Server crashes after receiving a request or reply message lost (cannot be told apart!)
  - Client resubmits request, server chooses:
    - Re-execute procedure: service should be idempotent
    - Filter duplicates: server should hold on to results until acknowledged
- Client crashes after sending a request
  - Orphan detection: reincarnations, expirations
- Reporting failures breaks transparency



Fault tolerance measures

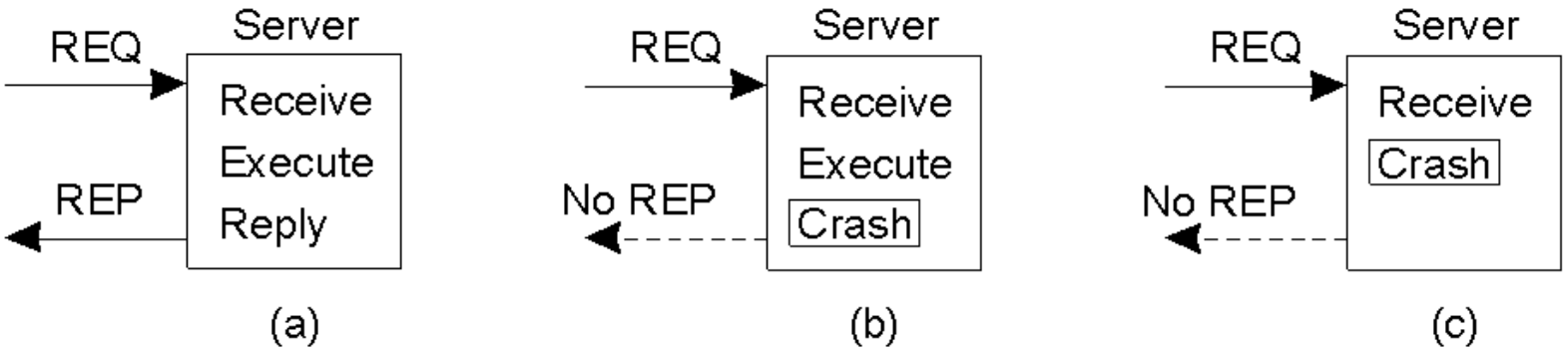
Retransmit request	Duplicate filtering	Re-execute/ retransmit	Invocation semantics
no	N/A	N/A	**maybe**
yes	no	re-execute	**at-least-once**
yes	yes	retransmit reply	**at-most-once**



Reliable Client-Server Communication

1. Point-to-Point Communication (“reliable”)
   - masked: omission, value
   - not masked: crash, (timing)
2. Recall the RPC failure classes:
   - the client unable to locate the server
   - a message is lost (request / reply)
   - the server crashes (before / during / after service)
   - the client crashes

Server Crashes



A server in client-server communication
a) Normal case
b) Crash after execution
c) Crash before execution

E.g.: Printer server crashes (Fig. 8-8)

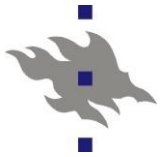
Client | **Printer Server ("print queue")**

Client's request reissue strategy	Strategy: Message client, then Print			Strategy: Print, then Message		
	MPC	**MC(P)**	**C(MP)**	**PMC**	**PC(M)**	**C(PM)**
Always (*at-least-once semantics*)	DUP	OK	OK	DUP	DUP	OK
Never (*maybe semantics*)	OK	ZERO	ZERO	OK	OK	ZERO
Only when not ACKed (*depends*)	OK	ZERO	OK	OK	DUP	OK
Only when ACKed (*madness!*)	**DUP**	OK	ZERO	**DUP**	OK	ZERO

Different combinations of client and server strategies in the presence of server crashes (client hears of crash, decides: reissue request / not?)

M: send the completion message
P: tell printer to print text
C: crash
ACK: Receipt of the completion message

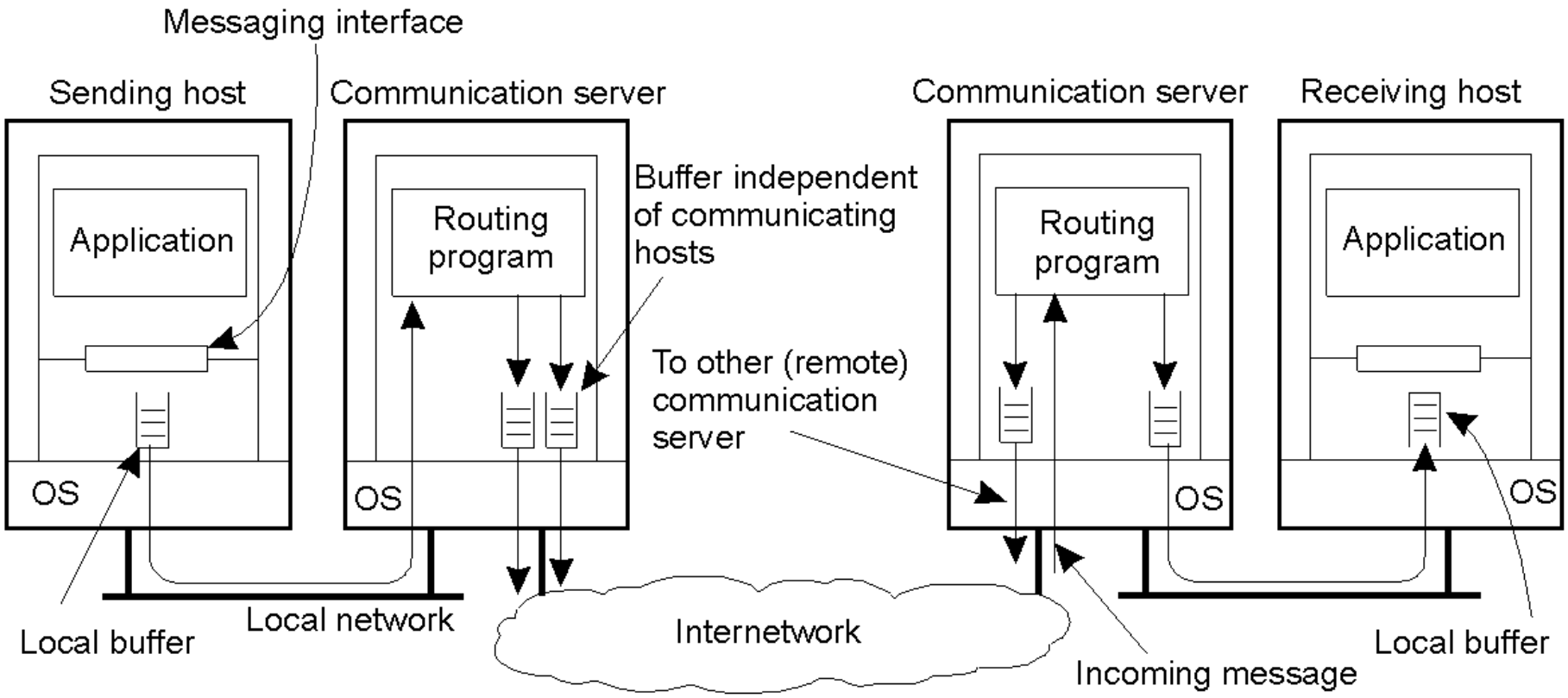
OK = Text printed once
DUP = Text printed twice
ZERO = Text not printed



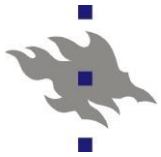
Client Crashes: No one there to receive a reply

- Orphan: an active computation looking for a non-existing parent
- Solutions
  - extermination: the client stub records all calls, after reboot any orphans on record are explicitly killed
  - reincarnation: time is divided into epochs, client reboot => broadcast “new epoch” => servers kill the client’s old requests
  - gentle incarnation: “new epoch” => look for parents, kill real orphans
  - expiration: a “time-to-live” for each RPC (+ possibility to request for a further time slice)
- New problems: grandorphans, reserved locks, entries in remote queues, ….

Persistence and Synchronicity in Communication



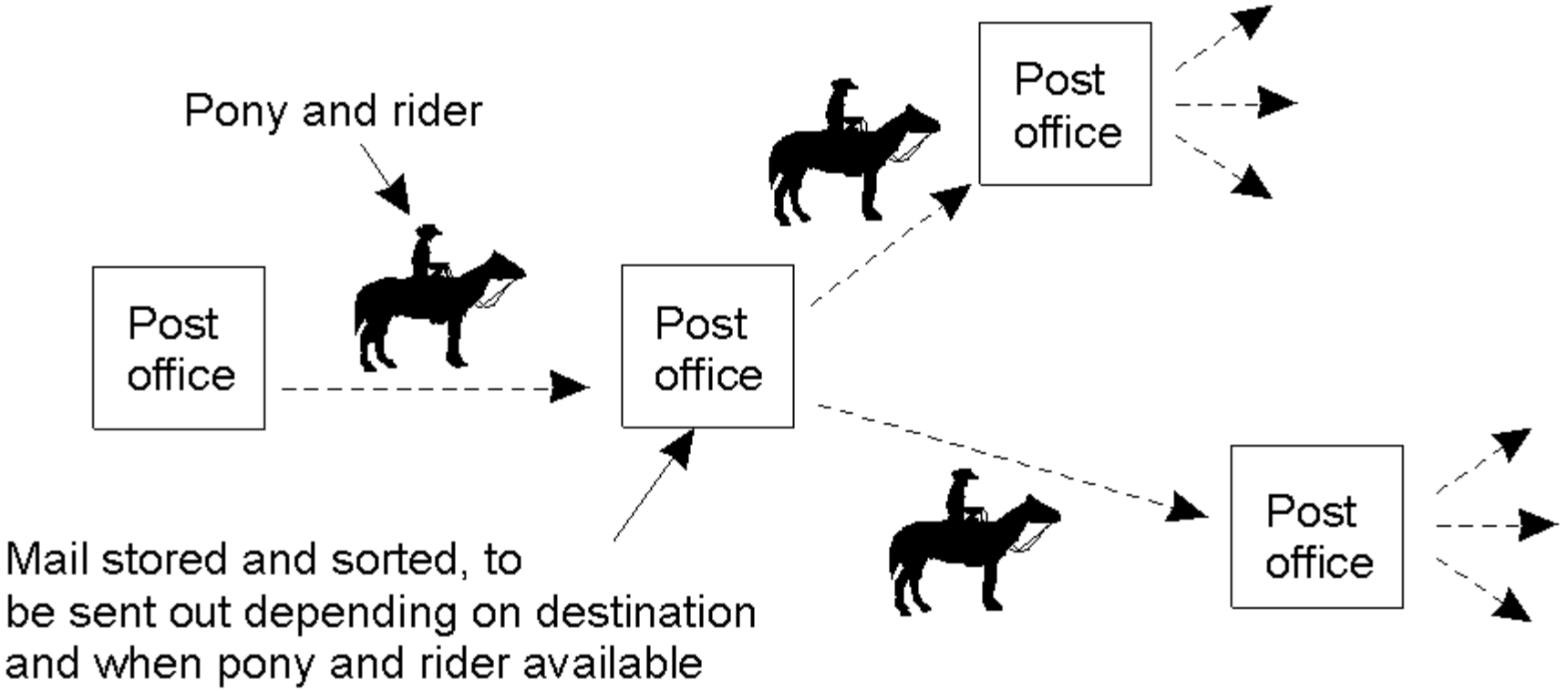
General organization of a communication system in which hosts are connected through a network



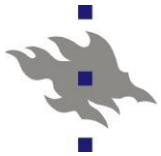
Persistent vs. Transient Communication

- Persistent communication
  - A submitted message is stored in the system until delivered to the receiver
  - (the receiver may start later, the sender may stop earlier)
- Transient communication
  - A message is stored only as long as the sending and receiving applications are executing
  - (the sender and the receiver must be executing in parallel)

Persistent Communication – Pony Express Style



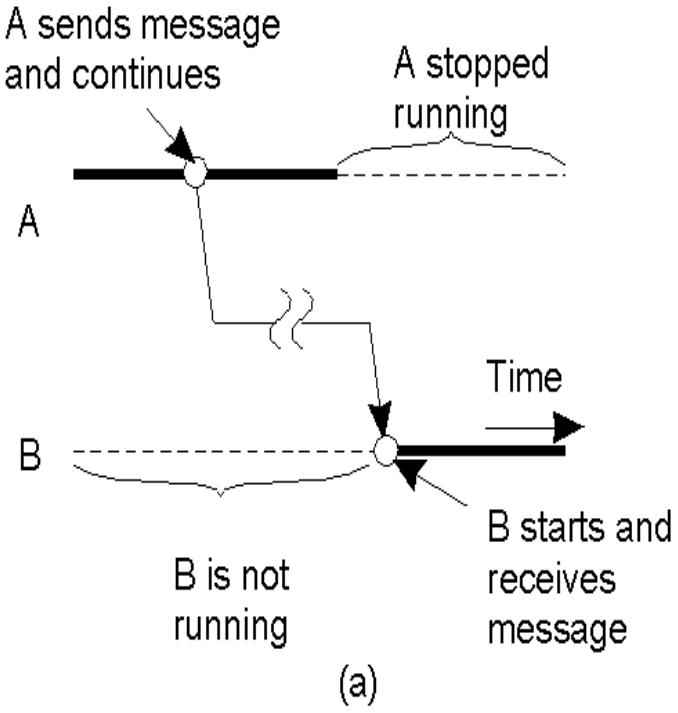
Persistent communication of letters back in the days of the Pony Express.

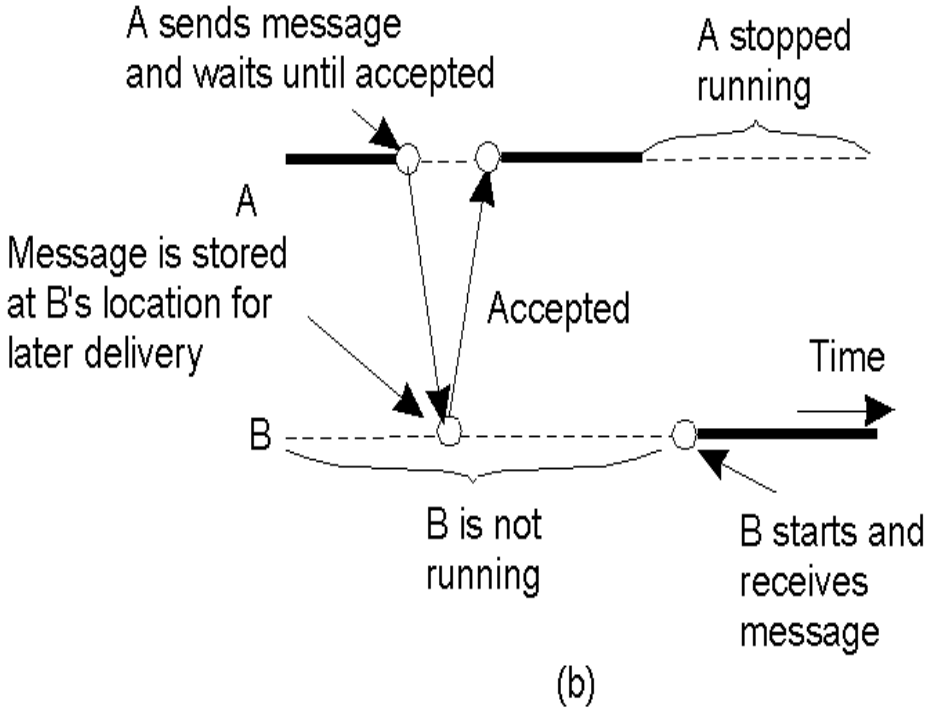


Sychronous and Asynchronous Communication

- Asynchronous communication
  - the sender continues immediately after submission; something else takes care of the rest
- Synchronous communication
  - the sender is blocked until
    - the message is received by e.g. middleware to deliver to target application (receipt-based synchrony)
    - the message is delivered to the target (delivery based)
    - the response to it has arrived (response based)

Persistence and Synchronicity in Communication

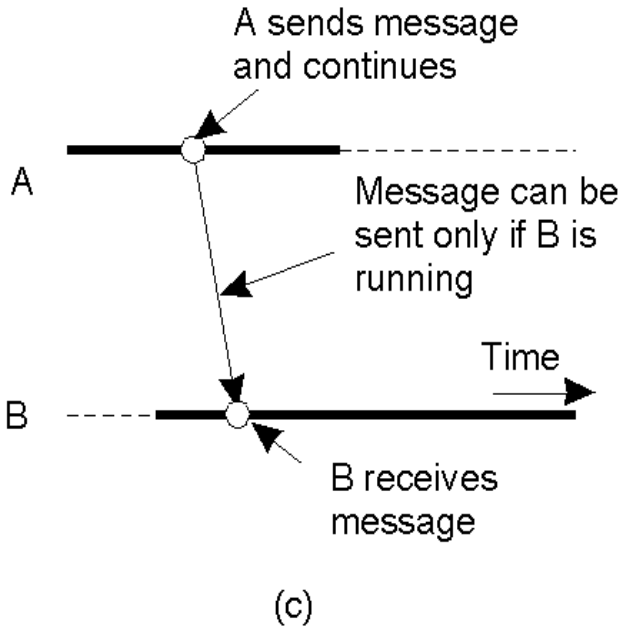


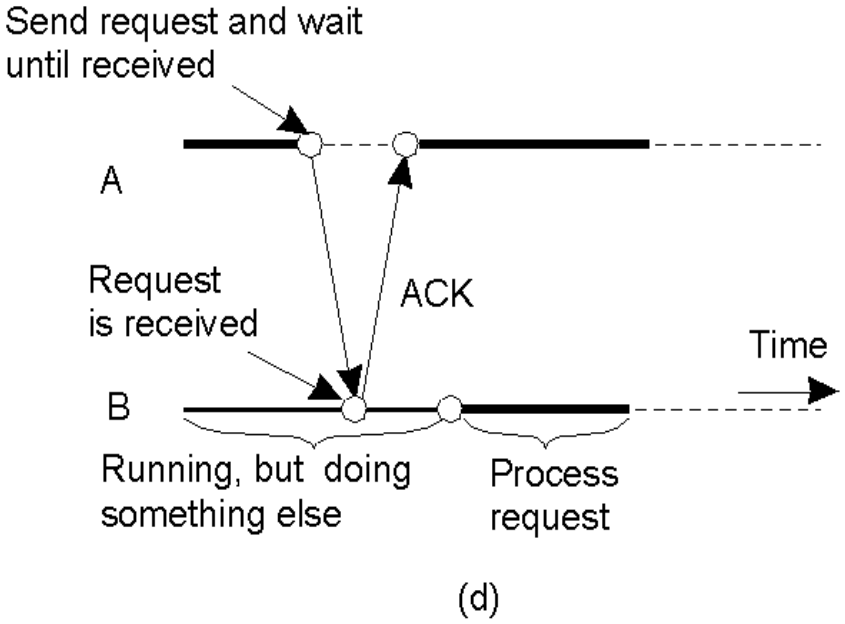


a) Persistent asynchronous communication

b) Persistent (delivery-based) synchronous communication

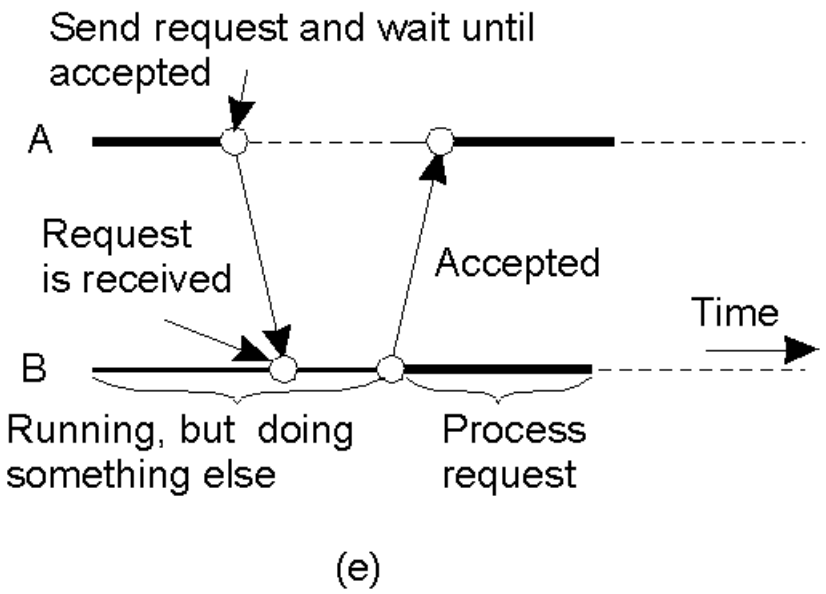
Persistence and Synchronicity in Communication



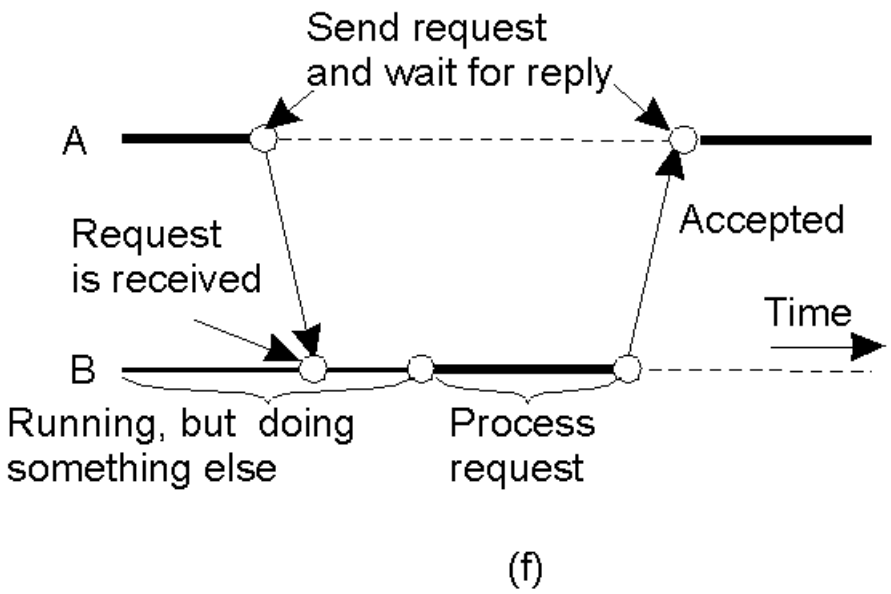


c) Transient asynchronous communication
d) Receipt-based transient synchronous communication

Persistence and Synchronicity in Communication

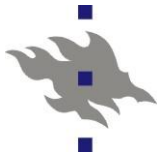


(e)



(f)

e) Delivery-based transient synchronous communication at message delivery
f) Response-based transient synchronous communication



Chapter Summary

- Overview of interprocess communication
- Remote invocations (RPC etc.)
- Persistence and synchronicity